## Series 6DOF25000E

Electric Motion Platform


## > 6 Degrees of Freedom

> 10,500 Kg/23, 150 lbs Customer Installed Payload
> Modular Actuator and Joint Design
> 100\% Electric Actuation
> 100\% Digital Control Electronics and Power Amplifiers

## Worldwide Support

## North \& South America:

Moog Inc., Industrial Controls Division, East Aurora, New York 14052-0018
Telephone: 716/655-3000 • Fax: 716/687-4401

## Europe:

Moog Controls Ltd., Tewkesbury, United Kingdom • Telephone: +44(0) 1684-296600 • Fax: +44(0) 1684-296760
Moog GmbH, Böblingen, Germany • Telephone: +49(0)7031-622-0 • Fax: +49(0)703 1-622-100
Moog Sarl, Cedex, France • Telephone: +33(0) 145607000 • Fax: $+33(0) 145607001$
Moog Sarl Sucursal En España, Orio, Spain • Telephone: +34(0)9 43133240•Fax: +34(0)943133180

## Pacific:

Moog Australia Pty. Ltd., Mulgrave, Australia • Telephone: +61 (0)3 9561-6044 • Fax: +61 (0)3 9562-0246
Moog Japan Ltd., Hiratsuka, Japan • Telephone: +81 (0)463-55-3615 • Fax: +81 (0)463-54-4709

## Series 6DOE25000:

## Moog Inc.

Moog Industrial Controls offers high performance solutions to motion simulator requirements. Fifty years of experience and a proven track record makes Moog the world's leading supplier of motion system components and integrated platforms in both the training and entertainment markets.

Moog produces both 4 degree and 6 degree of freedom (DOF) motion bases, with actuator strokes ranging from 12 to 62 inches and load capacities up to $14,600 \mathrm{Kg}(32,200 \mathrm{lbs})$.

## Specifications: 6DOF25000E Size:

Settled Height
(top of joint interface)....2.5 m (82.94") (with 60" stroke)
Foot Print. $\qquad$ $.6 .3 \mathrm{~m}(\mathrm{w}) \times 5.5 \mathrm{~m}$ (247" $(\mathrm{w}) \times 215^{\prime \prime}$ )
System Weight
(actuators and joints) .... $6170 \mathrm{Kg}(13,600 \mathrm{lbs}$ )

## Facility:

Floor Loading Compression
Average Operating
(0.8 g heave) ............ $6347 \mathrm{Kg} / \mathrm{m}^{2}$
$\left(1300 \mathrm{lb} / \mathrm{ft}^{2}\right)$
Main....................... $3 \phi, 460-500$ vac.
$50-60 \mathrm{~Hz}$

## Load:

Max. Flying Payload.. $11,430 \mathrm{Kg}(25,200 \mathrm{lbs})$ Max. Customer Added Payload
$.10,500 \mathrm{Kg}(23,150 \mathrm{lbs})$
CG Location
Horizontal ............ $\leq 0.15 \mathrm{~m}\left(6.0^{\prime \prime}\right)$
Vertical ................ $\leq 1.78$ m (70")
(above the motion centroid)
Motion Centroid .....0.152 m (6.0")
(below the top of the platform joints)
Mass Moment of Inertia
(relative to motion centroid)
Pitch Axis $\qquad$ $67,790 \mathrm{Kg}-\mathrm{m}^{2}$ (50,000 Slug-ftr$)$
Roll Axis. $\qquad$ $67,790 \mathrm{Kg}-\mathrm{m}^{2}$ (50,000 Slug- $\mathrm{ft}^{2}$ )
Yaw Axis.............. $54,230 \mathrm{Kg}-\mathrm{m}^{2}$ (40,000 Slug-ftr$)$

## Actuator Features:

- 60" Stroke Actuators
- DC Brushless Servomotor
- In-line motor design, direct drive
- High efficiency, low friction actuator design
- Ballscrew or rollerscrew design available
- Patented internal hydraulic snubbers
- High resolution absolute encoder feedback
- Home limit switches
- Motors contain internal thermal protection


## Documentation:

- Facility Requirements
- Installation Instructions
- Operation/Maintenance Manual


## Reliability:

- Custom high efficiency drives and actuators optimized for performance and long life in demanding applications.
Designed for a minimum 10 year life.
- Detailed fault tree analysis for all single point and multiple failure modes has been performed.
- Drives have been life cycle tested and have proven field history.


## Field Service and Repair:

- One (1) year part warranty from the date of shipment
- Worldwide support
- Installation and training support provided


## Compliance:

- The system is designed to U.S. and European electrical codes.
- The system utilizes UL and CE compliant components.
- Designed to meet the AFGS-87241A requirement to egress to home position in event of major single point failures.
- Electronics are CE marked


## Interface Options:

Ethernet or Firewire Interface

- Profile Storage
- Real Time
- Real Time with Motion Cueing (Motion Dynamics Algorithm)


## Motion System Interfaces:



Motion:

|  |  |  | $\begin{aligned} & \lambda \\ & \vdots \\ & 0 \\ & \vdots \\ & \hline 0 \end{aligned}$ | $\begin{aligned} & \text { 듷 } \\ & \text { 음 } \\ & \frac{1}{0} \\ & \hline \mathbb{U} \\ & 4 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| Pitch | $+36.3 \mathrm{deg}$ <br> -32.4 deg | $\begin{aligned} & +26.3 \mathrm{deg} \\ & \text {-24.0 deg } \end{aligned}$ | $\pm 21.6 \mathrm{deg} / \mathrm{s}$ | $\pm 200 \mathrm{deg} / \mathrm{s}^{2}$ |
| Roll | $\pm 32.5 \mathrm{deg}$ | $\pm 26.2 \mathrm{deg}$ | $\pm 24.0 \mathrm{deg} / \mathrm{s}$ | $\pm 200 \mathrm{deg} / \mathrm{s}^{2}$ |
| Yaw | $\pm 35.1 \mathrm{deg}$ | $\pm 32.9 \mathrm{deg}$ | $\pm 28.9 \mathrm{deg} / \mathrm{s}$ | $\pm 200 \mathrm{deg} / \mathrm{s}^{2}$ |
| Heave | $\begin{gathered} \pm 0.87 \mathrm{~m} \\ ( \pm 34.4 \mathrm{in}) \end{gathered}$ | $\begin{gathered} \pm 0.88 \mathrm{~m} \\ ( \pm 34.7 \mathrm{in}) \end{gathered}$ | $\begin{gathered} \pm 0.77 \mathrm{~m} / \mathrm{s} \\ ( \pm 30.2 \mathrm{in} / \mathrm{s}) \end{gathered}$ | $\pm 0.8 \mathrm{~g}$ |
| Surge | $\begin{aligned} & +1.39,-1.42 \mathrm{~m} \\ & (+54.8,-56.0 \mathrm{in}) \end{aligned}$ | $\binom{+1.32,-1.08 \mathrm{~m}}{(+52.0,-42.5 \mathrm{in})}$ | $\begin{gathered} \pm 1.03 \mathrm{~m} / \mathrm{s} \\ ( \pm 40.7 \mathrm{in} / \mathrm{s}) \end{gathered}$ | $\pm 1.0 \mathrm{~g}$ |
| Sway | $\begin{aligned} & \pm 1.54 \mathrm{~m} \\ & ( \pm 60.5 \mathrm{in}) \end{aligned}$ | $\begin{array}{r}  \pm 1.09 \mathrm{~m} \\ ( \pm 42.9 \mathrm{in}) \end{array}$ | $\begin{gathered} \pm 1.05 \mathrm{~m} / \mathrm{s} \\ ( \pm 41.2 \mathrm{in} / \mathrm{s}) \end{gathered}$ | $\pm 1.0 \mathrm{~g}$ |

Specifications are subject to change without notice

